

EP 20 Core and accessories

Series/Type: B65847, B65848

Date: June 2013



EP 20

Core B65847

- To IEC 61596
- For transformers featuring high inductance and low overall height
- For power applications
- Delivery mode: sets

Magnetic characteristics (per set)

 $\Sigma I/A = 0.51 \text{ mm}^{-1}$

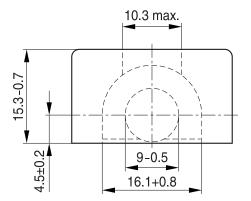
 $I_{e} = 40 \text{ mm}$

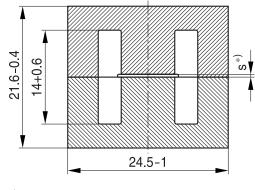
 $A_{e} = 78 \text{ mm}^{2}$

 $A_{min} = 60 \text{ mm}^2$

 $V_e = 3120 \text{ mm}^3$

Approx. weight 27.5 g/set





*) gapped (one-sided)

FEP0081-N-E

Gapped

Material	A _L value	S	μ_{e}	Ordering code
	nH	approx. mm		
N87	200 ±3%	0.47	82	B65847A0200A087

Ungapped

Material	A _L value	μ_{e}	P _V	Ordering code
	nH		W/set	
N30	6700 +30/–20%	2730		B65847A0000R030
T65	10200 +30/–20%	4160		B65847A0000R065
T38	18700 +40/-30%	7630		B65847A0000Y038
N87	4000 +30/–20%	1630	< 1.2 (200 mT, 100 kHz, 100 °C)	B65847A0000R087



EP 20

Accessories B65848

Coil former

Material: GFR thermosetting plastic (UL 94 V-0, insulation class to IEC 60085:

F

max. operating temperature 155 °C), color code green

Vyncolit/X611® [E167521 (M)], VYNCOLIT NV

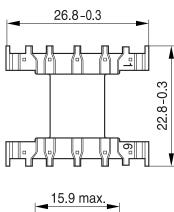
Solderability: to IEC 60068-2-20, test Ta, method 1 (aging 3): 235 °C, 2 s

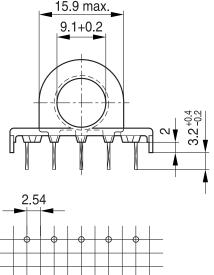
Resistance to soldering heat: to IEC 60068-2-20, test Tb, method 1B: 350 °C, 3.5 s

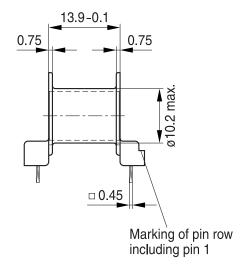
Winding: see Data Book 2013, chapter "Processing notes, 2.1"

Squared pins.

Sections	A _N mm ²	I _N mm	A_R value $\mu\Omega$	Terminals	Ordering code
1	35.4	40.6	39.5	10	B65848D1010D001







FEP0083-W-E

Ground 1.3+0.2



EP 20

Accessories B65848

Mounting assembly

The set comprises a yoke and a clamp

Yoke

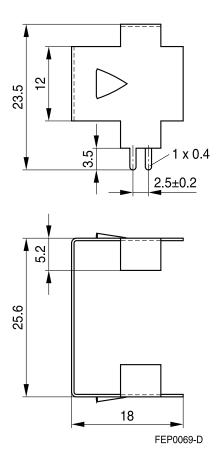
Made of nickel bronze (0.4 mm) with ground terminal (tinned)

Clamp

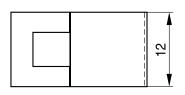
Spring clamp, made of stainless spring steel (0.4 mm)

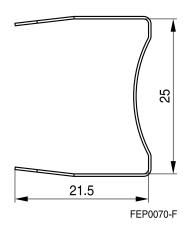
	Ordering code
Complete mounting assembly	B65848A2000X000

Yoke



Clamp







Cautions and warnings

Mechanical stress and mounting

Ferrite cores have to meet mechanical requirements during assembling and for a growing number of applications. Since ferrites are ceramic materials one has to be aware of the special behavior under mechanical load.

As valid for any ceramic material, ferrite cores are brittle and sensitive to any shock, fast changing or tensile load. Especially high cooling rates under ultrasonic cleaning and high static or cyclic loads can cause cracks or failure of the ferrite cores.

For detailed information see chapter "Definitions", section 8.1.

Effects of core combination on A₁ value

Stresses in the core affect not only the mechanical but also the magnetic properties. It is apparent that the initial permeability is dependent on the stress state of the core. The higher the stresses are in the core, the lower is the value for the initial permeability. Thus the embedding medium should have the greatest possible elasticity.

For detailed information see chapter "Definitions", section 8.2.

Heating up

Ferrites can run hot during operation at higher flux densities and higher frequencies.

NiZn-materials

The magnetic properties of NiZn-materials can change irreversible in high magnetic fields.

Processing notes

- The start of the winding process should be soft. Else the flanges may be destroid.
- To strong winding forces may blast the flanges or squeeze the tube that the cores can no more be mount.
- To long soldering time at high temperature (>300 °C) may effect coplanarity or pin arrangement.
- Not following the processing notes for soldering of the J-leg terminals may cause solderability problems at the transformer because of pollution with Sn oxyd of the tin bath or burned insulation of the wire. For detailed information see chapter "Processing notes", section 8.2.
- The dimensions of the hole arrangement have fixed values and should be understood as a recommendation for drilling the printed circuit board. For dimensioning the pins, the group of holes can only be seen under certain conditions, as they fit into the given hole arrangement. To avoid problems when mounting the transformer, the manufacturing tolerances for positioning the customers' drilling process must be considered by increasing the hole diameter.



Symbols and terms

Symbol	Meaning	Unit
A	Cross section of coil	mm ²
A_{e}	Effective magnetic cross section	mm ²
A_L	Inductance factor; $A_L = L/N^2$	nH
A_{L1}	Minimum inductance at defined high saturation ($\triangleq \mu_a$)	nH
A_{min}	Minimum core cross section	mm ²
A _N	Winding cross section	mm ²
A_R	Resistance factor; $A_R = R_{Cu}/N^2$	$\mu\Omega = 10^{-6} \Omega$
В	RMS value of magnetic flux density	Vs/m ² , mT
ΔΒ	Flux density deviation	Vs/m ² , mT
Ê	Peak value of magnetic flux density	Vs/m ² , mT
ΔÂ	Peak value of flux density deviation	Vs/m ² , mT
B_{DC}	DC magnetic flux density	Vs/m², mT
B _R	Remanent flux density	Vs/m ² , mT
B_S	Saturation magnetization	Vs/m², mT
C_0	Winding capacitance	F = As/V
CDF	Core distortion factor	mm ^{-4.5}
DF	Relative disaccommodation coefficient DF = d/μ_i	
d	Disaccommodation coefficient	
Ea	Activation energy	J
f	Frequency	s−1, Hz
f _{cutoff}	Cut-off frequency	s ⁻¹ , Hz
f _{max}	Upper frequency limit	s⁻¹, Hz
f _{min}	Lower frequency limit	s⁻¹, Hz
f _r	Resonance frequency	s⁻¹, Hz
f_{Cu}	Copper filling factor	
g	Air gap	mm
Н	RMS value of magnetic field strength	A/m
Ĥ	Peak value of magnetic field strength	A/m
H_{DC}	DC field strength	A/m
H _c	Coercive field strength	A/m
h	Hysteresis coefficient of material	10 ⁻⁶ cm/A
h/μ_i^2	Relative hysteresis coefficient	10 ⁻⁶ cm/A
I	RMS value of current	Α
I_{DC}	Direct current	Α
Î	Peak value of current	Α
J	Polarization	Vs/m ²
k	Boltzmann constant	J/K
k_3	Third harmonic distortion	
k _{3c}	Circuit third harmonic distortion	
L	Inductance	H = Vs/A



Symbols and terms

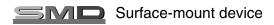
Symbol	Meaning	Unit
Δ L/L	Relative inductance change	Н
L_0	Inductance of coil without core	Н
L _H	Main inductance	Н
L_p	Parallel inductance	Н
L _{rev}	Reversible inductance	Н
L _s	Series inductance	Н
l _e	Effective magnetic path length	mm
I _N	Average length of turn	mm
N	Number of turns	
P_{Cu}	Copper (winding) losses	W
P _{trans}	Transferrable power	W
P _V	Relative core losses	mW/g
PF	Performance factor	
Q	Quality factor (Q = $\omega L/R_s$ = 1/tan δ_L)	
R	Resistance	Ω
R_{Cu}	Copper (winding) resistance (f = 0)	Ω
R _h	Hysteresis loss resistance of a core	Ω
ΔR_h	R _h change	Ω
R _i	Internal resistance	Ω
R _p	Parallel loss resistance of a core	Ω
Rs	Series loss resistance of a core	Ω
R_{th}	Thermal resistance	K/W
R _V	Effective loss resistance of a core	Ω
S	Total air gap	mm
Т	Temperature	°C
ΔT	Temperature difference	K
T_{C}	Curie temperature	°C
t	Time	s
t_{v}	Pulse duty factor	
tan δ	Loss factor	
tan δ_L	Loss factor of coil	
$tan \delta_r$	(Residual) loss factor at $H \rightarrow 0$	
$tan \delta_e$	Relative loss factor	
tan δ_h	Hysteresis loss factor	
tan δ/μ_i	Relative loss factor of material at H \rightarrow 0	
U	RMS value of voltage	V
Û	Peak value of voltage	V
V _e	Effective magnetic volume	mm ³
Z	Complex impedance	Ω
Z _n	Normalized impedance $ Z _n = Z /N^2 \times \varepsilon (l_e/A_e)$	Ω/mm



Symbols and terms

Symbol	Meaning	Unit
α	Temperature coefficient (TK)	1/K
α_{F}	Relative temperature coefficient of material	1/K
α_{e}	Temperature coefficient of effective permeability	1/K
ϵ_{r}	Relative permittivity	
Φ	Magnetic flux	Vs
η	Efficiency of a transformer	
η _B	Hysteresis material constant	mT ⁻¹
η _i	Hysteresis core constant	$A^{-1}H^{-1/2}$
λ_{s}	Magnetostriction at saturation magnetization	
μ	Relative complex permeability	
μ_0	Magnetic field constant	Vs/Am
μ_{a}	Relative amplitude permeability	
$\mu_{\sf app}$	Relative apparent permeability	
μ_{e}	Relative effective permeability	
μ_{i}	Relative initial permeability	
μ_{p}^{l}	Relative real (inductive) component of $\overline{\mu}$ (for parallel components)	
μ _p "	Relative imaginary (loss) component of $\overline{\mu}$ (for parallel components)	
μ_{r}	Relative permeability	
$\mu_{\sf rev}$	Relative reversible permeability	
μ_{s}	Relative real (inductive) component of $\overline{\mu}$ (for series components)	
μ_{S} "	Relative imaginary (loss) component of $\overline{\mu}$ (for series components)	
μ_{tot}	Relative total permeability	
	derived from the static magnetization curve	
ρ	Resistivity	Ω m $^{-1}$
ΣI/A	Magnetic form factor	mm ⁻¹
^τ Cu	DC time constant $\tau_{Cu} = L/R_{Cu} = A_L/A_R$	S
ω	Angular frequency; $\omega = 2 \Pi f$	s ⁻¹

All dimensions are given in mm.





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